Redundant information, total information and higher order interactions

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DEMICS – MPI PKS

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1 The functional form of redundant information

2 The total information lattice

Section 1: The functional form of redundant information



Does the redundant information depend on the full distribution,

$$I_{\cap}(T; \boldsymbol{A}_1, \dots, \boldsymbol{A}_k) = f(P(T, \boldsymbol{A}_1, \dots, \boldsymbol{A}_k))?$$

• Or does it only depend on the marginal distributions,

$$I_{\cap}(T; \boldsymbol{A}_1, \dots, \boldsymbol{A}_k) = f(P(T, \boldsymbol{A}_1), \dots, P(T, \boldsymbol{A}_k))?$$



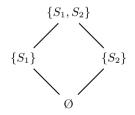
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- Power set can be ordered by set inclusion yielding the inclusion lattice

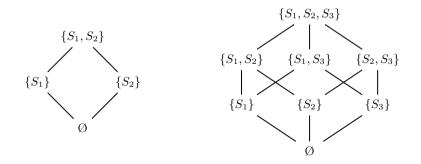


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Partial information decomposition

- Mutual information $I(T; \mathbf{A})$ quantifies the information provided by a single source
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The Williams and Beer Axioms

1 Symmetry: $I_{\cap}(T; A_1, \dots, A_k)$ is invariant under permutations of the A_i 's

2 Self-redundancy:
$$I_{\cap}(T; \mathbf{A}_i) = I(T; \mathbf{A})$$

3 Monotonicity: $I_{\cap}(T; \boldsymbol{A}_1, \dots, \boldsymbol{A}_k) \leq I_{\cap}(T; \boldsymbol{A}_1, \dots, \boldsymbol{A}_{k-1})$

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- What are the different ways the sources can provide redundant information?
 - Answering this question corresponds to determining the domain of I_{\cap}



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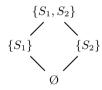
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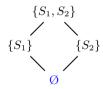




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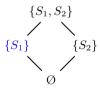




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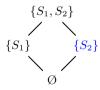
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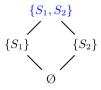
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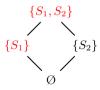
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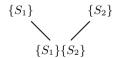
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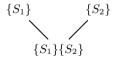


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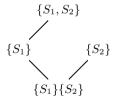


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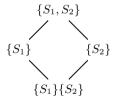


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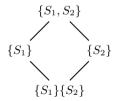


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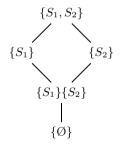


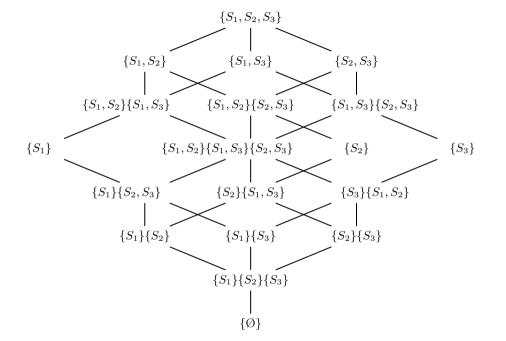
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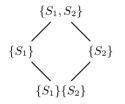




Missing details



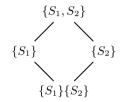
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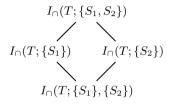


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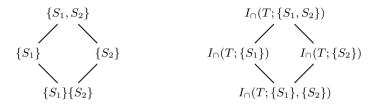
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• Leaves the door open to differing interpretations:

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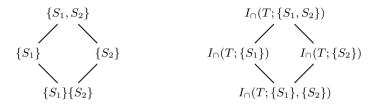
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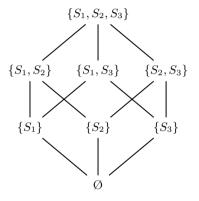
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Why are we talking about sets of random variables?

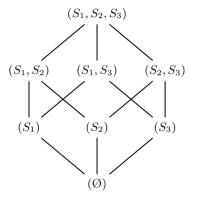


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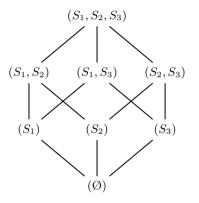




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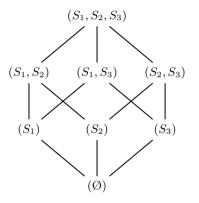


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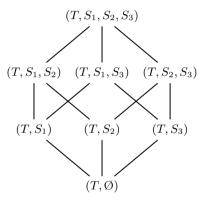


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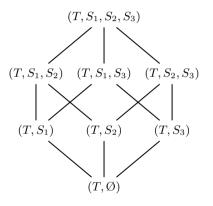
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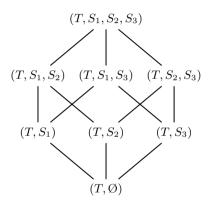
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- \blacksquare Lattice of all marginal vectors of (T, \boldsymbol{S}) containing T
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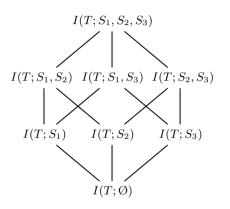
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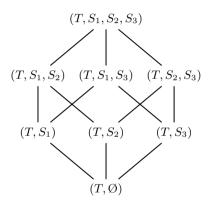
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Domain of the redundancy function for vectors

Axiom 2 specifies the function form of redundant information for a single source

$$I_{\cap}(T; \boldsymbol{A}) = I(T; \boldsymbol{A}) = f((T, \boldsymbol{A}))$$

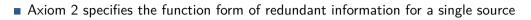
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Extending this dependence to multiple marginal vectors

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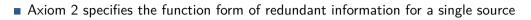
Extending this dependence to multiple marginal vectors

$$I_{\cap}(T; \boldsymbol{A}_1, \dots, \boldsymbol{A}_k) = f((T, \boldsymbol{A}_1), \dots, (T, \boldsymbol{A}_k))$$

• Many collections of marginal vectors are equivalent due to Axiom 3, e.g.

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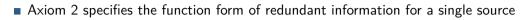
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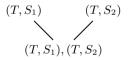
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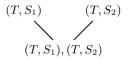


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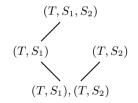
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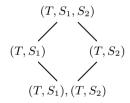




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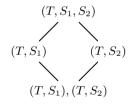
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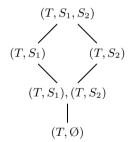
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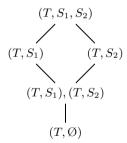




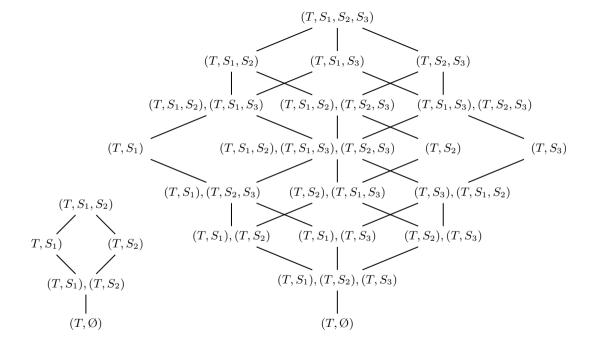
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■ Redundant information only depends on the marginal distributions $I_{\cap}(T; \{S_1\}, \{S_2\}) = f(P(T, S_1), P(T, S_2))$



Functional dependence of redundant information

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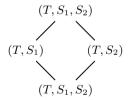
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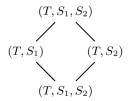
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Section 2: The total information lattice



- $\blacksquare~I_{\cap}$ quantifies the redundant information a collection of sources provide about T
- Can we instead quantify the total information I_{\cup} the sources provide about T?



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$$I_{\cup}(T; \boldsymbol{A}_1, \dots, \boldsymbol{A}_k) = f((T, \boldsymbol{A}_1), \dots, (T, \boldsymbol{A}_k))$$

- if we knew the full distribution, then just use the (joint) mutual information



Axioms

1 Symmetry: $I_{\cup}(T; A_1, \dots, A_k)$ is invariant under permutations of the A_i 's

2 Self-redundancy:
$$I_{\cup}(T; \mathbf{A}_i) = I(T; \mathbf{A})$$

3 Monotonicity: $I_{\cup}(T; A_1, \dots, A_k) \ge I_{\cup}(T; A_1, \dots, A_{k-1})$ with equality if $A_{k-1} \supseteq A_k$



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- What are the different ways the sources can provide total information?
 - Answering this question corresponds to determining the domain of I_{\cup}



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- Many collection are equivalent due to Axiom 3, e.g. since $\{S_1\} \subseteq \{S_1, S_2\}$,

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 - same domain as the redundancy functions I_{\cap}





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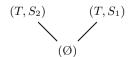


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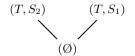
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$$I_{\cup}(T; \{S_1, S_2\}) = I_{\cup}(T; \{S_1\}, \{S_2\}, \{S_1, S_2\}) \ge I_{\cup}(T; \{S_1\}, \{S_2\})$$
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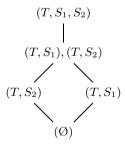
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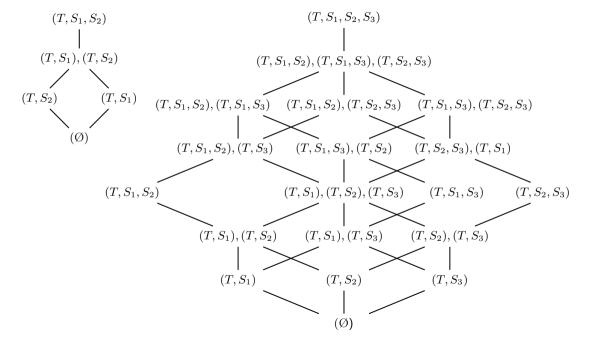
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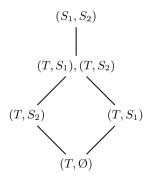
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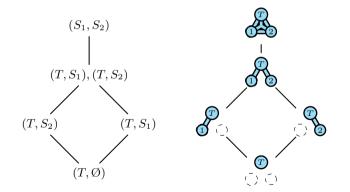
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- no assumption about inclusion-exclusion here



 \blacksquare The partial information atoms I_∂ are non-negative iff I_\cap is totally monotone

$$I_{\cap}(T; \bigvee_{1 \le j \le k} \alpha_j) \ge \sum_{\emptyset \ne J \subseteq \{1, \dots, k\}} (-1)^{|J|-1} I_{\cap}(T; \bigwedge_{j \in J} \alpha_j)$$

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- for $\alpha_1 = \{S_1\}$, $\alpha_2 = \{S_2\}$ and $\alpha_2 = \{S_2\}$

$$\begin{split} I\big(T;(S_1,S_2,S_3)\big) &\geq I(T;S_1) + I(T;S_2) + I(T;S_3) \\ &\quad -I_{\cap}(T;S_1,S_2) - I_{\cap}(T;S_1,S_3) - I_{\cap}(T;S_2,S_3) \\ &\quad +I_{\cap}(T;S_1,S_2,S_3) \end{split}$$

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$$I(T; (S_1, S_2, S_3)) \ge I(T; S_1) + I(T; S_2) + I(T; S_3) - I_{\cap}(T; S_1, S_2) - I_{\cap}(T; S_1, S_3) - I_{\cap}(T; S_2, S_3) + I_{\cap}(T; S_1, S_2, S_3)$$

$$\begin{aligned} &-\text{ for } \alpha_1 = \{S_1, S_2\}, \ \alpha_2 = \{S_1, S_3\} \text{ and } \alpha_2 = \{S_2, S_3\} \\ &I\big(T; (S_1, S_2, S_3)\big) \geq I\big(T; (S_1, S_2)\big) + I\big(T; (S_1, S_3)\big) + I\big((T; (S_2, S_3)\big) \\ &-I_{\cap}\big(T; (S_1, S_2), (S_1, S_3)\big) - I_{\cap}\big(T; (S_1, S_2), (S_2, S_3)\big) - I_{\cap}\big(T; (S_1, S_3), (S_2, S_3)\big) \\ &+I_{\cap}\big(T; (S_1, S_2), (S_1, S_3), (S_2, S_3)\big) \end{aligned}$$

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- for $\alpha_1=\{S_1\}\text{, }\alpha_2=\{S_2\}$ and $\alpha_2=\{S_2\}$

$$I(T; (S_1, S_2, S_3)) \ge I(T; S_1) + I(T; S_2) + I(T; S_3) - I_{\cap}(T; S_1, S_2) - I_{\cap}(T; S_1, S_3) - I_{\cap}(T; S_2, S_3) + I_{\cap}(T; S_1, S_2, S_3)$$

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 \blacksquare Total monotonicity for I_{\cap} fails and when a connected I_{\cup} fails to be monotonic





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– We also need to consider the union information I_{\cup}



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– Easier to consider the monotonicity of I_{\cup} than total monotonicity of I_{\cup}